Condition Monitoring: Technology For Assessing Vehicle And Track Performance

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June 6th 2017







Summary

What's *inside* the technology?

Overview of measurement systems.

What is the future of measurement?







Background on Sensors







Distance/Location Measurement



Wheel Sensor



Tachometer (aka Wheel Encoder)



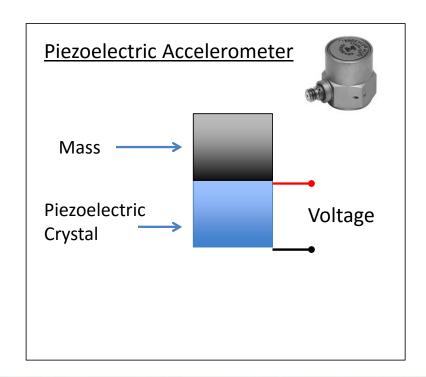
GPS Antenna
Differential Correction
Inertial Correction







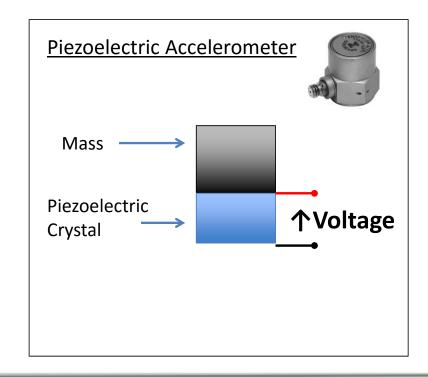
- Directly measure acceleration
- Acceleration can be converted to Velocity, Distance, and Force







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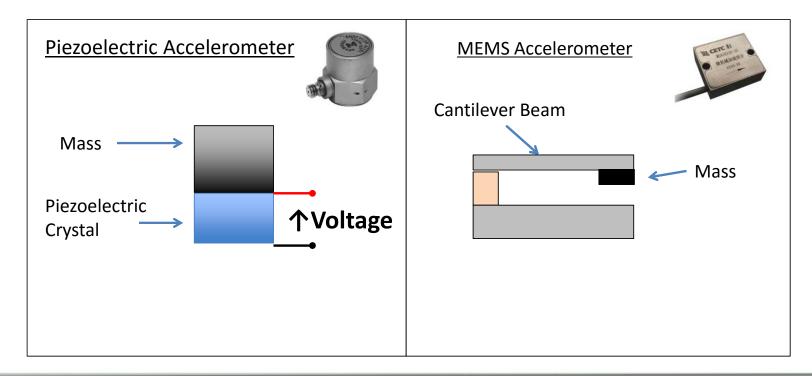








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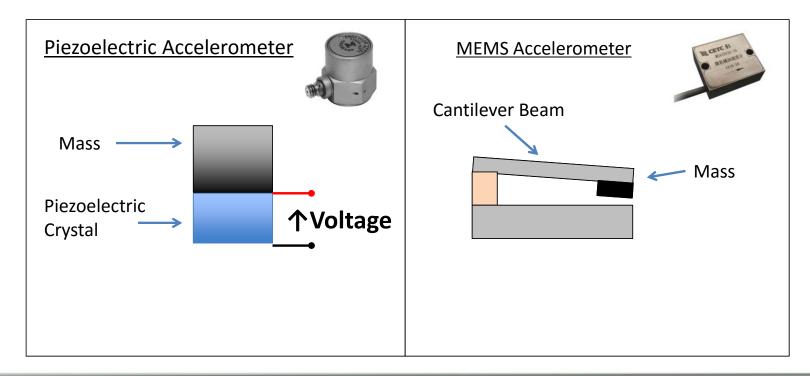








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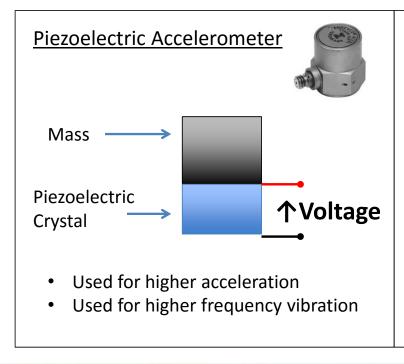


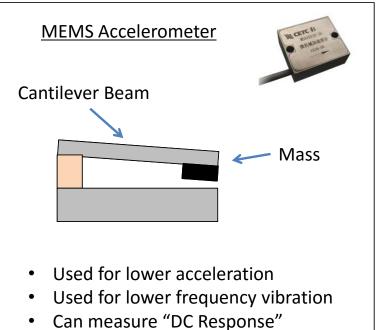






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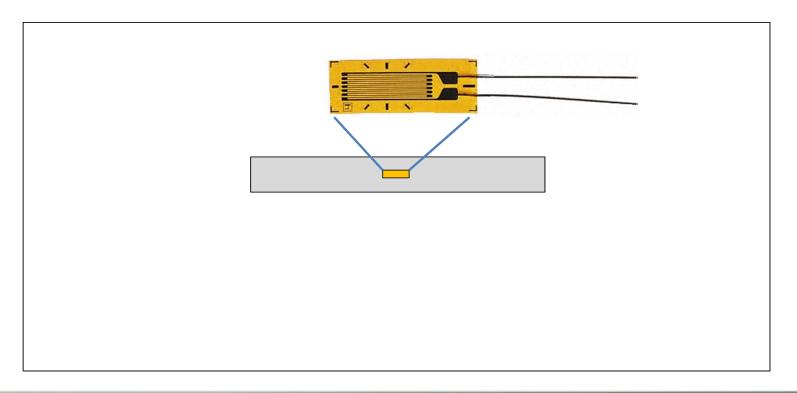






Strain Gauges

• Directly measures strain, which can be converted to stress.

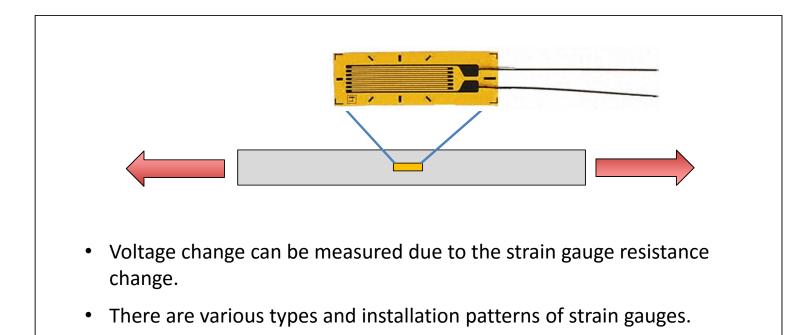






Strain Gauges

• Directly measures strain, which can be converted to stress.







Temperature Sensors

Thermistors and RTDs



- Uses resistance change to measure temperature.
- Lower cost
- Lower temperature range

Thermocouples



- Uses voltage change between dissimilar metals to measure temperature.
- Higher cost
- Higher temperature range

Infrared Sensors



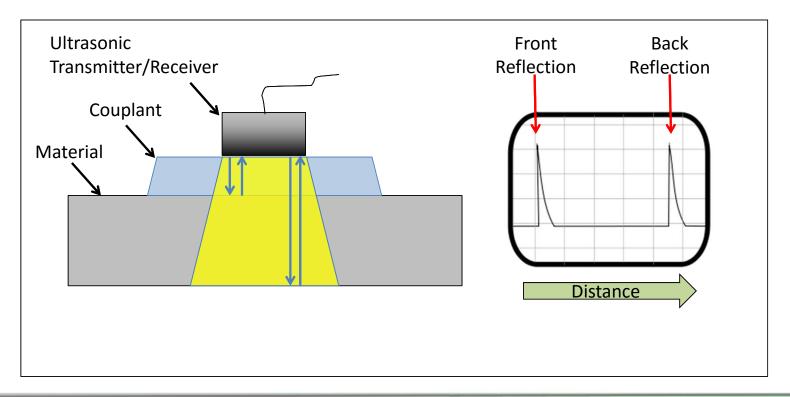
- Measures thermal radiation
- Non-contact measurement
- Sensitive to surface conditions





Ultrasonic Sensors

• Can measure depth, size, and orientation of internal flaws in a material

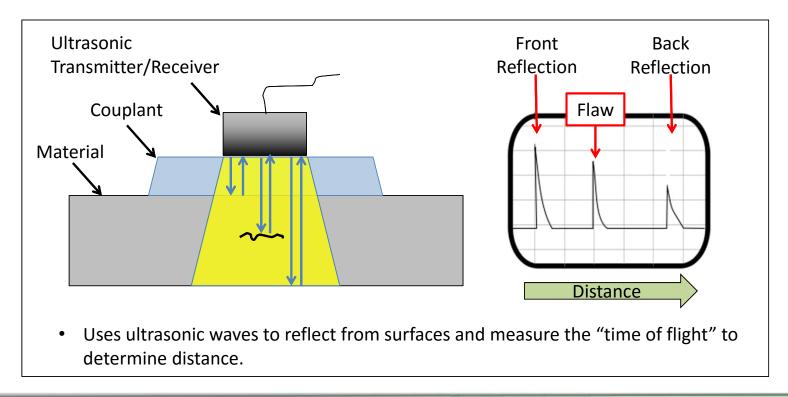






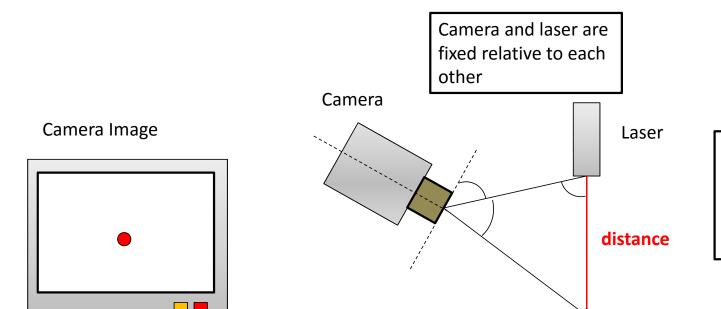
Ultrasonic Sensors

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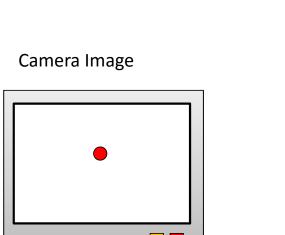


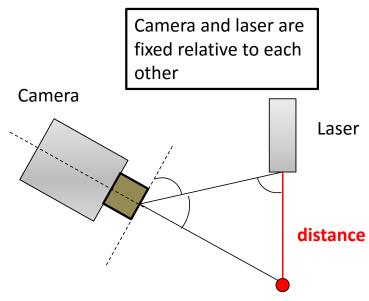
Use location of laser in camera image to triangulate distance







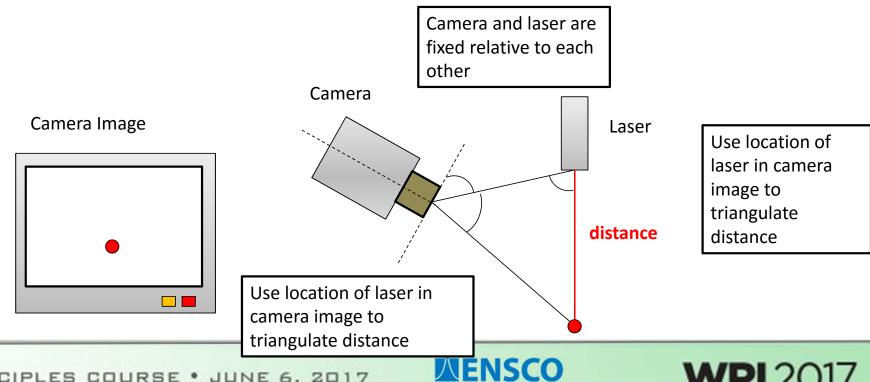




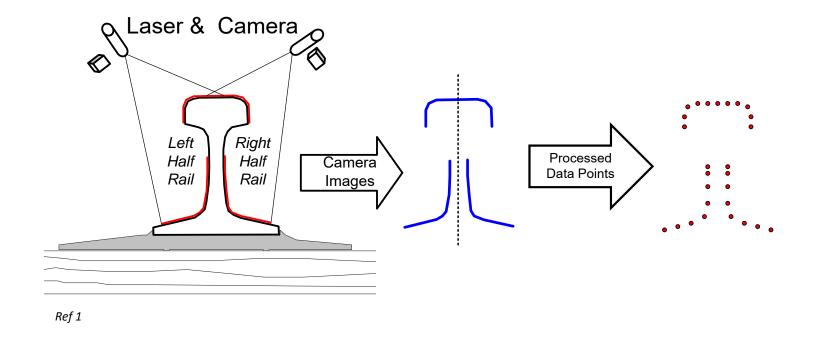
Use location of laser in camera image to triangulate distance





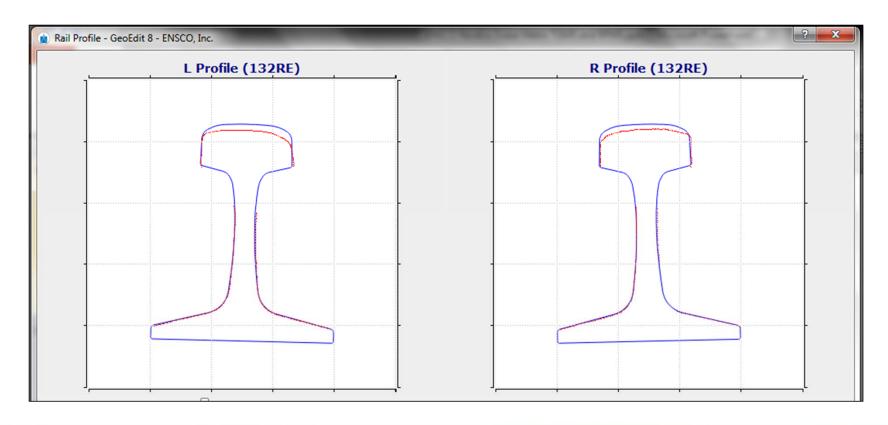


WRI 2017















"Line Scan" Cameras aka "Slit Scan"

Works like your document scanner

"Area Scan" Cameras aka "Full Frame"

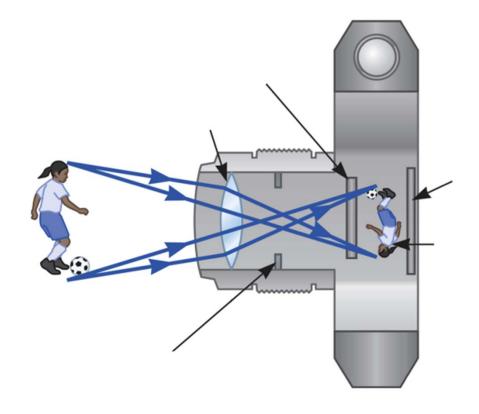
Works like your standard camera







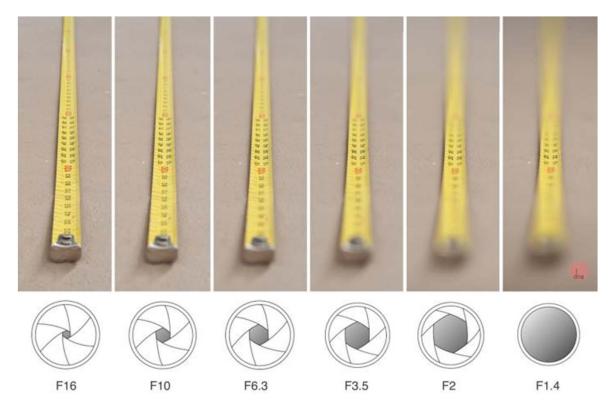




Ref: http://www.physics.byu.edu/faculty/colton/courses/phy123-fall12/warmups/jitt30a.html







Ref: https://www.ormsdirect.co.za/blog/2012/05/08/what-is-aperture-desmond-louw-explains/





What is needed for a railroad application:

Ideally want large depth of field (small aperture) for maximum content in focus.

Want **fast shutter speed** to capture quickly moving objects.

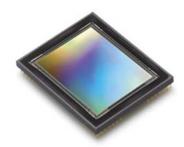
Generally need lots of light.











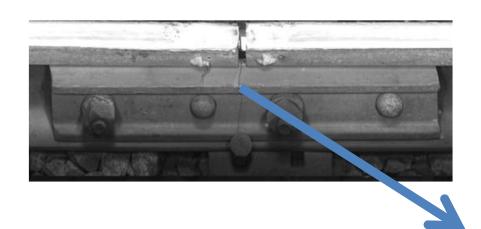
Area Scan Sensor

Light is converted to electricity similar to a solar cell.

Imagery sensors are like a grid of very tiny solar cells.



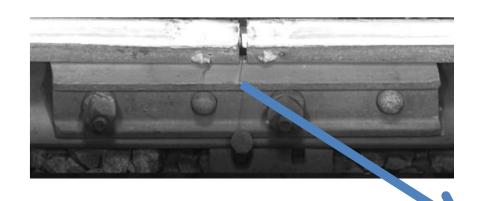












169	164	161	168	113	123	138	134	134	134
176	164	155	185	118	138	154	155	138	134
153	164	126	157	117	151	159	148	134	132
115	118	106	113	97	134	135	122	113	107
101	97	97	100	84	91	90	93	91	83
97	95	97	103	76	78	86	88	90	88
97	96	98	101	83	83	96	96	97	96
97	97	100	100	95	85	96	94	97	95
97	97	101	101	95	71	98	100	99	99





Overview of Measurement Systems

There are five basic categories of measurement system.





1) Mounted on <u>Vehicle</u> to measure the <u>Vehicle</u>.















1) Mounted on <u>Vehicle</u> to measure the <u>Vehicle</u>.

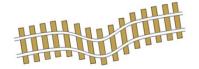
PRINCIPLES COURSE . JUNE 6, 2017



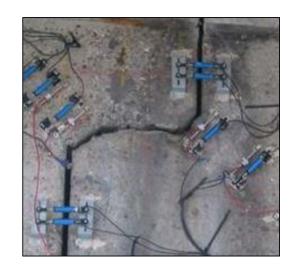
System	Accel	Strain	Temp	Ultra- sonic	Laser	Camera	Other
Event Recorder							Pressure, Throttle, etc
Locomotive Health Monitor							Pressure, Fuel
Railcar Health Monitor							



2) Mounted on <u>Track</u> to measure the <u>Track</u>.



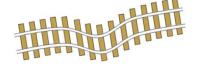








2) Mounted on <u>Track</u> to measure the <u>Track</u>.

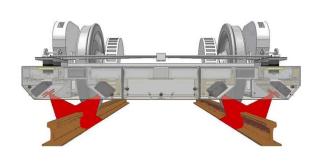


System	Accel	Strain	Temp	Ultra- sonic	Laser	Camera	Other
Rail Stress / Temp Monitor							
Bridge Monitoring							
Ballast & Formation Monitoring							Displacement
Landslip Monitoring							Displacement
Flood Monitoring							Water



3) Mounted on <u>Vehicle</u> to measure the <u>Track.</u> (Manned, Unmanned, and Autonomous)





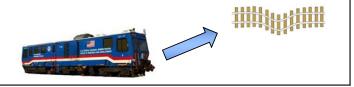








3) Mounted on <u>Vehicle</u> to measure the <u>Track.</u> (Manned, Unmanned, and Autonomous)



System	Accel	Strain	Temp	Ultra- sonic	Laser	Camera	Other
Track Geometry Measurement System							
Rail Profile Measurement System							
Ultrasonic Rail Flaw Detection							
Ground Penetrating Radar							Radar
Track Component, Joint Bar, & Rail Surface Machine Vision							
V/TI Monitors							
Corrugation Measurement							
Clearance Measurement & 3D Scanning							







4) Mounted on <u>Track</u> to measure the <u>Vehicle</u>.













4) Mounted on <u>Track</u> to measure the <u>Vehicle</u>.

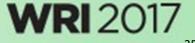
PRINCIPLES COURSE . JUNE 6, 2017



System	Accel	Strain	Temp	Ultra- sonic	Laser	Camera	Other
Dragging Equipment Detectors							Displacement
Hot Bearing & Hot/Cold Wheel Detectors							
Wheel Impact Load Detectors & Truck Performance Detectors							
Truck Condition Detector (TBOGI)							
Acoustic Bearing Detectors							Acoustic
Wheel Profile Detectors							
Cracked Wheel Detectors							
Machine Vision Systems							







5) Mounted on <u>Vehicle</u> to measure the <u>Vehicle & Track</u>.







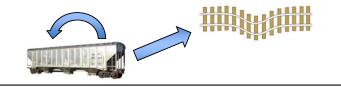






Categories of Measurement Systems

5) Mounted on <u>Vehicle</u> to measure the <u>Vehicle & Track</u>.



System	Accel	Strain	Temp	Ultra- sonic	Laser	Camera	Other
V/TI Monitors							
Instrumented Wheelsets							



Detailed Discussion of Measurement Systems



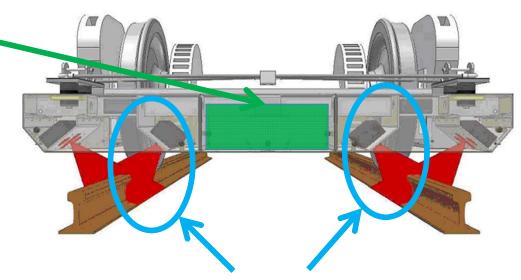




How does a Track Geometry Measurement System Work?

Inertial Package

"Measures the beam location in three dimensional space"



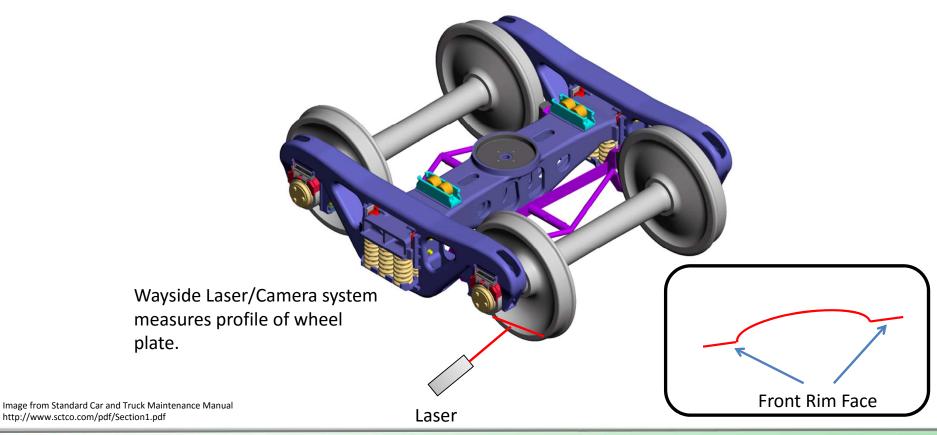
Laser/Cameras

"Measures the relative positions between the rails and the beam"





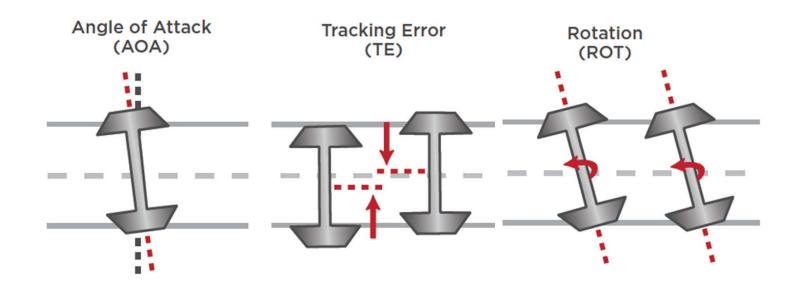
How does a truck condition monitor work?







How does a truck condition monitor work?

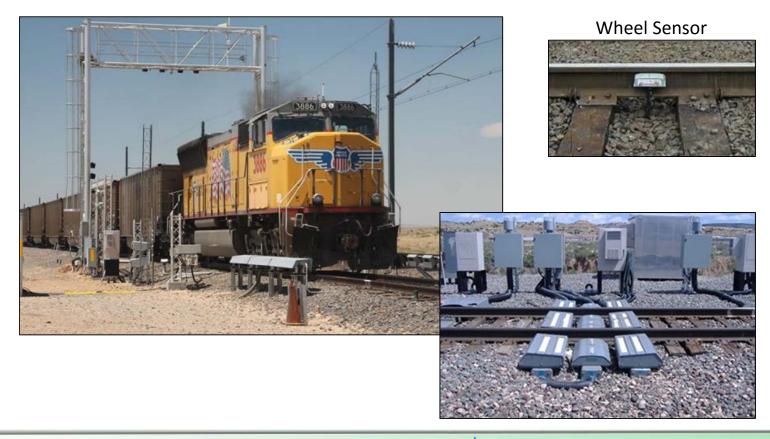


 $Images from \ Wayside \ Inspection \ Systems \\ http://wid.ca/sites/default/files/brochures/TBOGI/WID_TBOGI_Brochure_US.pdf$





Example Camera Systems

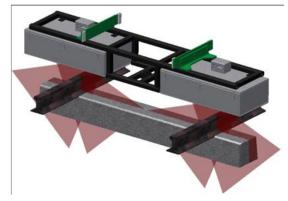




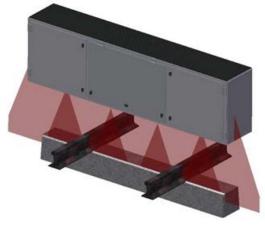


Example Camera Systems





Joint Bar View

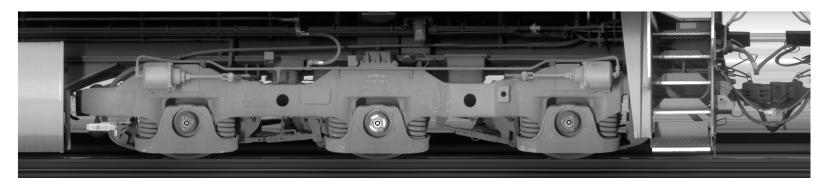


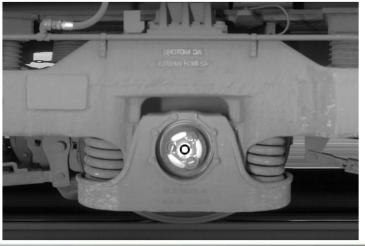
Track Bed View





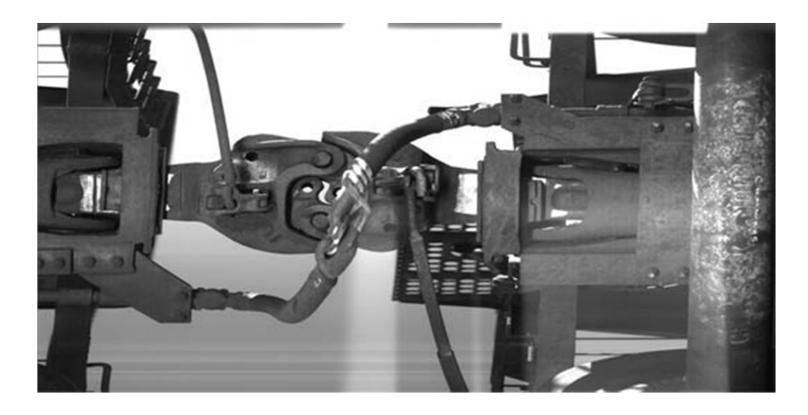






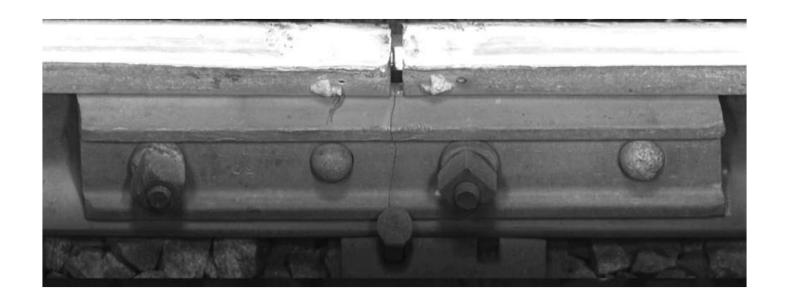


















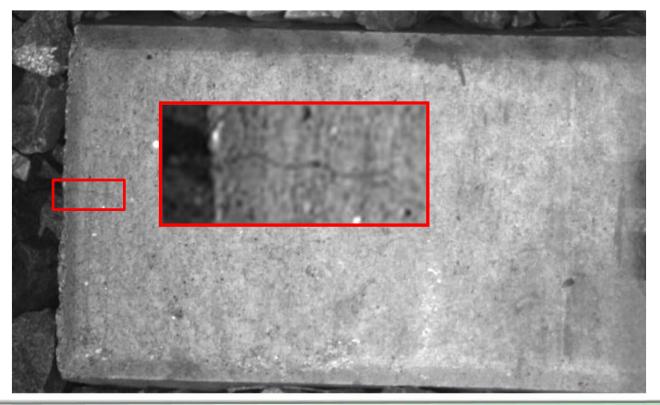






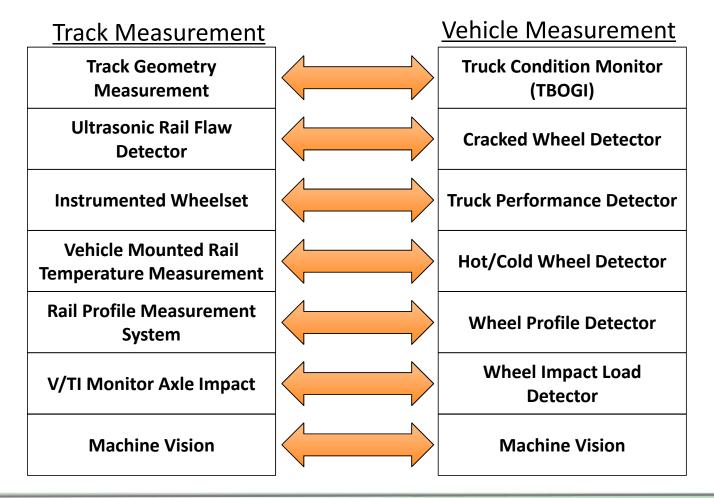
















What is the Future of Railway Measurement Technology?







1) Ultra Comprehensive Track Inspection Vehicles







Roy Hill Mine 2015
9 Inspection Systems

Track Geometry
Rail Profile
Corrugation
Ultrasonic Rail Flaw
Ground Penetrating Radar

Track Bed Imaging
Rail Surface Imaging
Driver View Imaging
Ballast/Formation Profile





Queensland Rail 2017 8 Inspection Systems

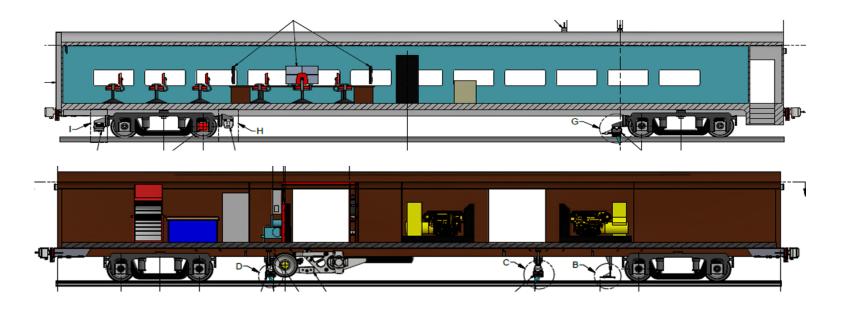
Track Geometry
Rail Profile
Corrugation
Clearance
Overhead Wire Measurement
Driver View Imaging
Track Component Imaging
Overhead Wire Imaging











Canadian Pacific 2019 8 Inspection Systems

Track Geometry Measurement System (TGMS)

Rail Profile Measurement System (RPMS)

Joint Bar Inspection System (JBIS)

Track Component Imaging System (TCIS)

Driver View Imaging System (DVIS)

Deployable Gage Restraint Measurement System (DGRMS)

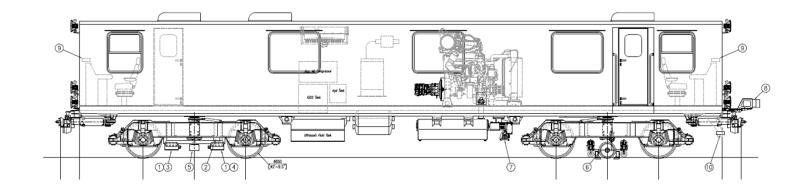
Loaded and Unloaded Gage

Grade Measurement









PATH 2018

10 Inspection Systems

Zero-Speed Track Geometry Measurement System (Z-TGMS)

Rail Profile Measurement System (RPMS)

Third Rail Measurement System (TRMS)

Tunnel Clearance Measurement System (TCMS)

Rail Corrugation Measurement System (RCMS)

Driver View Imaging System (DVIS)

Thermal Imaging System (TIS)

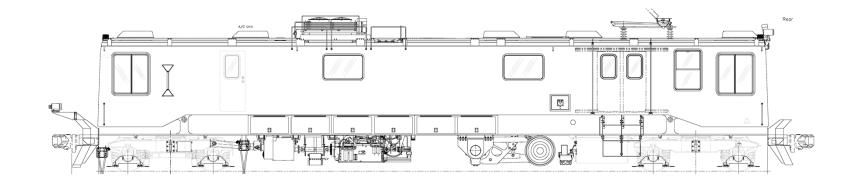
Rail Surface Imaging System (RSIS)

Tunnel Wall Imaging System (TWIS)

Ultrasonic Rail Flaw







Metro North Railroad 2018 12 Inspection Systems

Zero-Speed Track Geometry Measurement System (Z-TGMS)

Rail Profile Measurement System (RPMS)

Third Rail Measurement System (TRMS)

Tunnel Clearance Measurement System (TCMS)

Rail Corrugation Measurement System (RCMS)

Driver View Imaging System (DVIS)

Overhead Wire Measurement System (OWMS)

Deployable Gage Restraint Measurement System (DGRMS)

Loaded and Unloaded Gage

Signal and Communication Inspection System (SCIS)

Joint Bar Inspection System (JBIS)

Track Component Imaging System (TCIS)





2) Autonomous Track Inspection from Revenue Vehicles





2) Autonomous Track Inspection

Metro North Railroad 2016 Three (3) Units













2) Autonomous Track Inspection

Canadian Pacific - 2013



CSX - 2016



FRA - 2016



RUMO (Brazil) - 2017



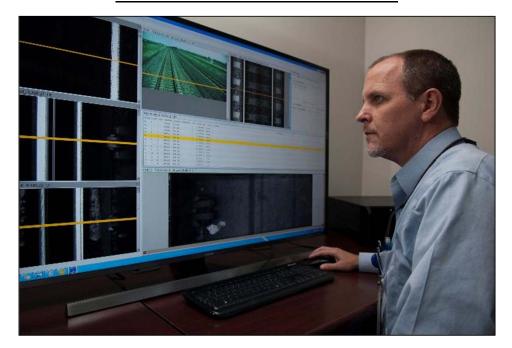




3) Field Inspections in the Office

- Increased safety
- Increased productivity and savings
- Additional increased savings from unmanned and autonomous systems on revenue vehicles

Virtual Track Walk Software









4) Unmanned Aerial Systems (UAS)

aka Unmanned Aerial Vehicles (UAV)

aka Drones (But don't call them Drones)







3) Unmanned Aerial Systems (UAS)

Multi-Rotor



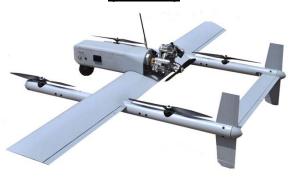
- Good maneuverability
- Relatively slow speed
- Lower altitude
- 20~40 minute flight time

Fixed Wing



- Good for flying long paths
- Relatively fast speed
- Higher altitude
- Several hours flight time

Vertical Take-Off and Landing (VTOL)



 Hybrid of multi-rotor and fixed wing





Questions?





